

## NILASAILA INSTITUTE OF SCIENCE & TECHNOLOGY SERGARH-756060, BALASORE (ODISHA) (Approved by AICTE& affiliated to SCTE&VT, Odisha)



## **LESSON PLAN**

**SUBJECT: TH-4 (CAD/CAM & AUTOMATION)** 

## **CHAPTER WISE DISTRIBUTION OF PERIODS**

SI.No.	Name of the chapter as per the Syllabus	No. of Periods as per the Syllabus	No. of periods actually needed
1	INTRODUCTION TO CAD/CAM	6	8
2	GEOMETRICMODELING	12	11
3	INTRODUCTION TO COMPUTER NUMERICAL CONTROL	6	6
4	PARTPROGRAMMING	14	14
5	INDUSTRIAL ROBOTICS	12	11
6	AUTOMATION	10	10
	Total Period:	60	62

Discipline: AUTOMOBILE ENGINEERING	Semester: 6th	Name of the Teaching Faculty: Er.Pradyumna Kumar Khilar		
		<b>SESSION</b> : 2023-24 <b>EXAMINATION</b> : 2024(S)		
Week	Class Day	Topics to be Covered		
1 <sup>st</sup>	1 <sup>st</sup>	1. Introduction to CAD / CAM		
	2 <sup>nd</sup>	Computers in industrial manufacturing.		
	3 <sup>rd</sup>	Computers in industrial manufacturing.		
	4 <sup>th</sup>	Product Cycle, CAD /CAM Hardware:Basicstructure, CPU, Memory, I/O devices Storage devices and system configuration.		
2 <sup>nd</sup>	1 <sup>st</sup>	Product Cycle, CAD /CAM Hardware:Basic structure, CPU, Memory, I/O devices, Storage devices and system configuration.		
	2 <sup>nd</sup>	Product Cycle, CAD /CAM Hardware:Basic structure, CPU, Memory, I/O devices, Storage devices and system configuration.		
	3 <sup>rd</sup>	2. Geometric Modelling :		
	4 <sup>th</sup>	2. Geometric Modelling :		
<b>3</b> <sup>rd</sup>	1 <sup>st</sup>	Requirement of geometric modeling.		
	2 <sup>nd</sup>	Requirement of geometric modeling.		
	3 <sup>rd</sup>	Types of Geometric models.		
	4 <sup>th</sup>	Types of Geometric models.		
<b>4</b> <sup>th</sup>	1 <sup>st</sup>	Types of Geometric models.		
	2 <sup>nd</sup>	Types of Geometric models.		
4	3 <sup>rd</sup>	Geometri construction method-sweep, solid moedlling – Primitives & Boolean operations, free		
	4 <sup>th</sup>	Geometri construction method-sweep, solid moedlling – Primitives & Boolean operations, free		
	1 <sup>st</sup>	Geometri construction method-sweep, solid moedlling – Primitives & Boolean operations, free		
<b>5</b> <sup>th</sup>	2 <sup>nd</sup>	Geometri construction method-sweep, solid moedlling – Primitives & Boolean operations, free		
5"	3 <sup>rd</sup>	3. Introduction to computer numerical Control		
	4 <sup>th</sup>	3. Introduction to computer numerical Control		
<b>6</b> <sup>th</sup>	1 <sup>st</sup>	Introduction – NC, CNC, DNC,		
	2 <sup>nd</sup>	Introduction – NC, CNC, DNC,		
	3 <sup>rd</sup>	Advantages of CNC		

Week	Class Day	Topics to be Covered
<b>6</b> <sup>th</sup>	4 <sup>th</sup>	Advantages of CNC
<b>7</b> <sup>th</sup>	1 <sup>st</sup>	Advantages of CNC
	2 <sup>nd</sup>	The coordinate system in CNC
	3 <sup>rd</sup>	The coordinate system in CNC
	4 <sup>th</sup>	Motion control system – point to point, straight line, Continuous path
8 <sup>th</sup>	1 <sup>st</sup>	Motion control system – point to point, straight line, Continuous path
	2 <sup>nd</sup>	Motion control system – point to point, straight line, Continuous path
	3 <sup>rd</sup>	Application of CNC.
	4 <sup>th</sup>	Application of CNC.
	1 <sup>st</sup>	4. Part programming :
9 <sup>th</sup>	2 <sup>nd</sup>	INTERNAL ASSESSMENT
	3 <sup>rd</sup>	INTERNAL ASSESSMENT
	4 <sup>th</sup>	Manual part programming
	1 <sup>st</sup>	Manual part programming
10 <sup>th</sup>	2 <sup>nd</sup>	NC- Words, Programming format
	3 <sup>rd</sup>	NC- Words, Programming format
	4 <sup>th</sup>	NC- Words, Programming format
11 <sup>th</sup>	1 <sup>st</sup>	Part programming
	2 <sup>nd</sup>	Part programming
	3 <sup>rd</sup>	use of subroutines and do loops,
	4 <sup>th</sup>	use of subroutines and do loops,
12 <sup>th</sup>	1 <sup>st</sup>	computer aided part programming
	2 <sup>nd</sup>	computer aided part programming
	3 <sup>rd</sup>	computer aided part programming
	4 <sup>th</sup>	5. Industrial Robotics

Week	Class Day	Topics to be Covered		
13 <sup>th</sup>	1 <sup>st</sup>	5. Industrial Robotics		
	2 <sup>nd</sup>	Introduction, physical configuration		
	3 <sup>rd</sup>	Introduction, physical configuration		
	4 <sup>th</sup>	basic robot motions, technical features such as work volume, precision and speed of movement, weight carrying capacity, drive system, End effectors, robot sensorsa		
14 <sup>th</sup>	1 <sup>st</sup>	basic robot motions, technical features such as work volume, precision and speed of movement, weight carrying capacity, drive system, End effectors, robot sensorsa		
	2 <sup>nd</sup>	basic robot motions, technical features such as work volume, precision and speed of movement, weight carrying capacity, drive system, End		
	3 <sup>rd</sup>	basic robot motions, technical features such as work volume, precision and speed of movement, weight carrying capacity, drive system, End effectors, robot sensorsa		
	4 <sup>th</sup>	Application- Material transfer, machine loading, welding, spray coating, processing operation, assembly, inspection.		
15 <sup>th</sup>	1 <sup>st</sup>	Application- Material transfer, machine loading, welding, spray coating, processing operation, assembly, inspection.		
	2 <sup>nd</sup>	opplication- Material transfer, machine loading, welding, spray coating, processing operation, assembly, inspection.		
	3 <sup>rd</sup>	Application- Material transfer, machine loading, welding, spray coating, processing operation, assembly, inspection.		
	4 <sup>th</sup>	6. Automation :		
16 <sup>th</sup>	1 <sup>st</sup>	Basic elements of automated system,		
	2 <sup>nd</sup>	advanced automation functions		
	3 <sup>rd</sup>	advanced automation functions		
	4 <sup>th</sup>	REVISION		