

**LESSON PLAN****SUBJECT:Th.3 (DIGITAL SIGNAL PROCESSING)****Name of the Faculty- Er.RAKESH KUMAR SETHI****Branch- Electrical & Electronics Engineering****Session- 2024-25****Semester- 6th****Examination- 2025(S)****CHAPTER WISE DISTRIBUTION OF PERIODS**

Sl.No.	Name of the chapter as per the Syllabus	No. of Periods as per the Syllabus	No. of periods actually needed
1	INTRODUCTION OF SIGNAL,SYSTEMS & SIGNAL PROCESSING	10	10
2	DISCRETE TIME SIGNALS & SYSTEMS	14	14
3	THE Z-TRANSFORM & ITS APPLICATION TO THE ANALYSIS OF	14	14
4	DISCUSS FOURIER TRANSFORM: ITS APPLICATIONS PROPERTIES	12	12
5	FAST FOURIER TRANSFORM ALGORITHM & DIGITAL FILTERS	10	10
TOTAL		60	60

SIGN OF FACULTY

SIGN HOD

Discipline: ELECTRICAL & ELECTRONICS ENGG.	Semester: 5TH	Name of the Teaching Faculty: Er. RAKESH KUMAR SETHI	
		SESSION : 2024-25	EXAMINATION : 2024 (W)
Week	Class Day	Theory / Practical Topics	
1 <sup>st</sup>	1 <sup>st</sup>	Introduction of Signals, Systems & Signal processing 1.1 Basics of Signals, Systems & Signal processing- basic element of a digital signal processing system -Compare the advantages of digital signal processing over analog signal processing.	
	2 <sup>nd</sup>	Introduction of Signals, Systems & Signal processing 1.1 Basics of Signals, Systems & Signal processing- basic element of a digital signal processing system -Compare the advantages of digital signal processing over analog signal processing.	
	3 <sup>rd</sup>	1.2 Classify signals - Multi channel & Multi-dimensional signals-Continuous time versus Discrete -time Signal. -Continuous valued versus Discrete -valued signals.	
	4 <sup>th</sup>	1.2 Classify signals - Multi channel & Multi-dimensional signals-Continuous time versus Discrete -time Signal. -Continuous valued versus Discrete -valued signals.	
	5 <sup>th</sup>	TUTORIAL	
2 <sup>nd</sup>	1 <sup>st</sup>	1.3 Concept of frequency in continuous time & discrete time signals-Continuous-time sinusoidal signals-Discrete-time sinusoidal signals-Harmonically related complex exponential.	
	2 <sup>nd</sup>	1.3 Concept of frequency in continuous time & discrete time signals-Continuous-time sinusoidal signals-Discrete-time sinusoidal signals-Harmonically related complex exponential.	
	3 <sup>rd</sup>	1.3 Concept of frequency in continuous time & discrete time signals-Continuous-time sinusoidal signals-Discrete-time sinusoidal signals-Harmonically related complex exponential.	
	4 <sup>th</sup>	1.4 Analog to Digital & Digital to Analog conversion & explain the following. a. Sampling of Analog signal,	
	5 <sup>th</sup>	TUTORIAL	



Week	Class Day	Theory / Practical Topics
3 <sup>rd</sup>	1 <sup>st</sup>	b. The sampling theorem. c. Quantization of continuous amplitude signals,
	2 <sup>nd</sup>	d. Coding of quantized sample. e. Digital to analog conversion. f. Analysis of digital systems signals vs. discrete time signals systems.
	3 <sup>rd</sup>	Concept of Discrete time signals. Elementary Discrete time signals.
	4 <sup>th</sup>	Concept of Discrete time signals. Elementary Discrete time signals.
	5 <sup>th</sup>	TUTORIAL
4 <sup>th</sup>	1 <sup>st</sup>	Classification Discrete time signal. Simple manipulation of discrete time signal.
	2 <sup>nd</sup>	Discrete time system. Input-output of system.
	3 <sup>rd</sup>	2.2.2 Block diagram of discrete- time systems
	4 <sup>th</sup>	Classify discrete time system. Inter connection of discrete -time system.
	5 <sup>th</sup>	TUTORIAL
5 <sup>th</sup>	1 <sup>st</sup>	Discrete time time-invariant system. Different techniques for the Analysis of linear system.
	2 <sup>nd</sup>	Resolution of a discrete time signal in to impulse. Response of LTI system to arbitrary inputs using convolution sum.
	3 <sup>rd</sup>	2.3.4 Convolution & interconnection of LTI system - properties.
	4 <sup>th</sup>	2.3.5 Study systems with finite duration and infinite duration impulse response.
	5 <sup>th</sup>	TUTORIAL

Week	Class Day	Theory / Practical Topics
6 <sup>th</sup>	1 <sup>st</sup>	Discrete time system described by difference equation. Recursive & non-recursive discrete time system.
	2 <sup>nd</sup>	2.4.2 Determine the impulse response of linear time invariant recursive system.
	3 <sup>rd</sup>	2.4.2 Determine the impulse response of linear time invariant recursive system.
	4 <sup>th</sup>	2.4.3 Correlation of Discrete Time signals
	5 <sup>th</sup>	TUTORIAL
7 <sup>th</sup>	1 <sup>st</sup>	3 THE Z-TRANSFORM & ITS APPLICATION TO THE ANALYSIS OF LTI SYSTEM. 3.1 Z-transform & its application to LTI system.
	2 <sup>nd</sup>	3 THE Z-TRANSFORM & ITS APPLICATION TO THE ANALYSIS OF LTI SYSTEM. 3.1 Z-transform & its application to LTI system.
	3 <sup>rd</sup>	3.1.1 Direct Z-transform.
	4 <sup>th</sup>	3.1.2 Inverse Z-transform.
	5 <sup>th</sup>	TUTORIAL
8 <sup>th</sup>	1 <sup>st</sup>	3.2 Various properties of Z-transform.
	2 <sup>nd</sup>	3.3 Rational Z-transform.
	3 <sup>rd</sup>	3.3.1 Poles & zeros
	4 <sup>th</sup>	3.3.2 Pole location time domain behaviour for casual signals.
	5 <sup>th</sup>	TUTORIAL



Week	Class Day	Theory / Practical Topics
	1 <sup>st</sup>	3.3.3 System function of a linear time invariant system.
9 <sup>th</sup>	2 <sup>nd</sup>	Discuss inverse Z-transform. Inverse Z-transform by partial fraction expansion
	3 <sup>rd</sup>	Discuss inverse Z-transform. Inverse Z-transform by partial fraction expansion
	4 <sup>th</sup>	TUTORIAL
10 <sup>th</sup>	1 <sup>st</sup>	3.4.2 Inverse Z-transform by contour Integration
	2 <sup>nd</sup>	3.4.2 Inverse Z-transform by contour Integration
	3 <sup>rd</sup>	4: DISCUSS FOURIER TRANSFORM: ITS APPLICATIONS PROPERTIES. 4.1 Concept of discrete Fourier transform.
	4 <sup>th</sup>	4.2 Frequency domain sampling and reconstruction of discrete time signals.
	5 <sup>th</sup>	TUTORIAL
11 <sup>th</sup>	1 <sup>st</sup>	4.2 Frequency domain sampling and reconstruction of discrete time signals.
	2 <sup>nd</sup>	4.3 Discrete Time Fourier transformation(DTFT)
	3 <sup>rd</sup>	4.3 Discrete Time Fourier transformation(DTFT)
	4 <sup>th</sup>	4.4 Discrete Fourier transformation (DFT).

	5 <sup>th</sup>	TUTORIAL
	Class Day	Theory / Practical Topics
12 <sup>th</sup>	1 <sup>st</sup>	4.5 Compute DFT as a linear transformation.
	2 <sup>nd</sup>	4.5 Compute DFT as a linear transformation.
	3 <sup>rd</sup>	4.6 Relate DFT to other transforms.
	4 <sup>th</sup>	4.6 Relate DFT to other transforms.
	5 <sup>th</sup>	TUTORIAL
13 <sup>th</sup>	1 <sup>st</sup>	4.7 Property of the DFT.
	2 <sup>nd</sup>	4.8 Multiplication of two DFT & circular convolution
	3 <sup>rd</sup>	5 FAST FOURIER TRANSFORM ALGORITHM & DIGITAL FILTERS. 5.1 Compute DFT & FFT algorithm.
	4 <sup>th</sup>	5.2 Direct computation of DFT.
	5 <sup>th</sup>	TUTORIAL
14 <sup>th</sup>	1 <sup>st</sup>	5.3 Divide and Conquer Approach to computation of DFT
	2 <sup>nd</sup>	5.4 Radix-2 algorithm. (Small Problems)
	3 <sup>rd</sup>	5.5 Application of FFT algorithms
	4 <sup>th</sup>	5.5 Application of FFT algorithms
	5 <sup>th</sup>	TUTORIAL

Week	Class Day	Theory / Practical Topics
15 <sup>th</sup>	1 <sup>st</sup>	5.6 Introduction to digital filters.(FIR Filters)& General considerations
	2 <sup>nd</sup>	5.7 Introduction to DSP architecture, familiarisation of different types of processor
	3 <sup>rd</sup>	5.7 Introduction to DSP architecture, familiarisation of different types of processor
	4 <sup>th</sup>	TUTORIAL

  
 SIGN OF FACULTY

  
 SIGN OF HOD