

## NILASAILA INSTITUTE OF SCIENCE & TECHNOLOGY SERGARH-756060, BALASORE (ODISHA) (Approved by AICTE& affiliated to SCTE&VT, Odisha)



## **LESSON PLAN**

SUBJECT: TH-2( ENERGY CONVERSION-II)

Name Of The Faculty:- Er. Shraddha Priyadarshini

Branch :- Electrical Engineering Semester :- 5th

Academic Year: 2025-26 Examination: - 2025 (W)

## **CHAPTER WISE DISTRIBUTION OF PERIODS**

SI.No.	Name of the chapter as per the Syllabus	No. of Periods as per the Syllabus	No. of periods actually needed
1	Alternator (Synchronous Generator)	14	14
2	Synchronous Motor	8	8
3	Induction motor	14	14
4	Single Phase induction motor	8	8
5	Commutator motors	6	6
6	Special Electric Machine	5	5
7	Three phase transformers	5	5
Total Period:			60

Shrachha Sign of Faculty

Sign of H.O.D.

Name of the programme: Diploma in Electrical Engineering	Semester: 5th	Name of the Teaching Faculty: Er. Shraddha Priyadarshini		
		Academic Year: 2025-26 Examination: 2025 (W		
Course Code: TH-2	Course Year: 3rd Year	No. of Classes Alloted Per Week :	4	
		Planned Classes Required to Complete the Course	60	
Week	Class Day	Topics to be Covered		
1 <sup>st</sup>	1 <sup>st</sup>	1. ALTERNATOR:图.1. Types of alternator and their constructional features		
	2 <sup>nd</sup>	1.2. Basic working principle of alternator and the relation between speed and frequency.		
	3 <sup>rd</sup>	1.2. Basic working principle of alternator and the relation between speed and frequency.		
	4 <sup>th</sup>	1.3. Terminology in armature winding and expressions for winding factors (Pitch factor, Distribution factor).		
	1 <sup>st</sup>	1.4. Explain harmonics, its causes and impact on winding factor		
2 <sup>nd</sup>	2 <sup>nd</sup>	1.4. Explain harmonics, its causes and impact on winding factor		
2	3 <sup>rd</sup>	1.5. E.M.F equation of alternator. (Solve numerical problems).		
	4 <sup>th</sup>	1.6. Explain Armature reaction and its effect on emf at different power factor of load.		
3 <sup>rd</sup>	1 <sup>st</sup>	1.6. Explain Armature reaction and its effect on emf at different power factor of load.		
	2 <sup>nd</sup>	1.7. The vector diagram of loaded alternator. (Solve numerical	problems)	
	3 <sup>rd</sup>	<ul><li>1.8. Testing of alternator (Solve numerical problems)</li><li>1.8.1. Open circuit test.</li></ul>		
	4 <sup>th</sup>	1.8.2. Short circuit test.		
	1 <sup>st</sup>	1.9. Determination of voltage regulation of Alternator by direct synchronous impedance method. (Solve numerical problems)	loading and	
<b>4</b> <sup>th</sup>	2 <sup>nd</sup>	1.10. Parallel operation of alternator using synchro-scope and omethod.	dark & bright lamp	
	3 <sup>rd</sup>	1.11. Explain distribution of load by parallel connected alternat	ors.	
	4 <sup>th</sup>	1.11. Explain distribution of load by parallel connected alternators.		
5 <sup>th</sup>	1 <sup>st</sup>	SYNCHRONOUS MOTOR: 2.1. Constructional feature of Synchronous Motor		
	2 <sup>nd</sup>	2.2. Principles of operation, concept of load angle		
	3 <sup>rd</sup>	2.3. Derive torque, power developed.		
	4 <sup>th</sup>	2.4. Effect of varying load with constant excitation. of varying excitation with constant load.	2.5. Effect	

Week	Class Day	Topics to be Covered		
<b>6</b> <sup>th</sup>	1 <sup>st</sup>	2.6. Power angle characteristics of cylindrical rotor motor.		
	2 <sup>nd</sup>	2.7. Explain effect of excitation on Armature current and power factor.		
	3 <sup>rd</sup>	2.8. Hunting in Synchronous Motor.		
	4 <sup>th</sup>	2.9. Function of Damper Bars in synchronous motor and generator.		
<b>7</b> <sup>th</sup>	1 <sup>st</sup>	2.10. Describe method of starting of Synchronous motor.		
	2 <sup>nd</sup>	2.11. State application of synchronous motor.		
	3 <sup>rd</sup>	THREE PHASE INDUCTION MOTOR: 3.1. Production of rotating magnetic field.		
	4 <sup>th</sup>	3.2. Constructional feature of Squirrel cage and Slip ring induction motors		
8 <sup>th</sup>	1 <sup>st</sup>	3.3. Working principles of operation of 3-phase Induction motor.		
	2 <sup>nd</sup>	3.4. Define slip speed, slip and establish the relation of slip with rotor quantities.		
	3 <sup>rd</sup>	3.5. Derive expression for torque during starting and running conditions and derive conditions for maximum torque. (solve numerical problems)		
	4 <sup>th</sup>	3.6. Torque-slip characteristics		
<b>9</b> <sup>th</sup>	1 <sup>st</sup>	3.7. Derive relation between full load torque and starting torque etc. (solve numerical problems)		
	2 <sup>nd</sup>	3.8. Establish the relations between Rotor Copper loss, Rotor output and Gross Torque and relationship of slip with rotor copper loss. (solve numerical problems)		
	3 <sup>rd</sup>	3.8. Establish the relations between Rotor Copper loss, Rotor output and Gross Torque and relationship of slip with rotor copper loss. (solve numerical problems)		
	4 <sup>th</sup>	3.9. Methods of starting and different types of starters used for three phase Induction motor.		
<b>10</b> <sup>th</sup>	1 <sup>st</sup>	changing, frequency control methods.		
	2 <sup>nd</sup>	3.11. Plugging as applicable to three phase induction motor		
	3 <sup>rd</sup>	3.12. Describe different types of motor enclosures . 3.13. Explain principle of Induction Generator and state its applications.		
	4 <sup>th</sup>	SINGLE PHASE INDUCTION MOTOR: 4.1. Explain Ferrari's principle		
11 <sup>th</sup>	1 <sup>st</sup>	4.2. Explain double revolving field theory and Cross-field theory to analyze starting torque of 1-phase induction motor.		
	2 <sup>nd</sup>	characteristics and application of following single phase motors.		
	3 <sup>rd</sup>	4.3.1. Split phase motor		

Week	Class Day	Topics to be Covered	
11 <sup>th</sup>	4 <sup>th</sup>	4.3.2. Capacitor Start motor. 4.3.3. Capacitor start, capacitor run motor	
<b>12</b> <sup>th</sup>	1 <sup>st</sup>	4.4. Explain the method to change the direction of rotation of above motors.	
	2 <sup>nd</sup>	5.1. Construction, working principle, running characteristic and application of single phase series motor.	
	3 <sup>rd</sup>	5.1. Construction, working principle, running characteristic and application of single phase series motor.	
	4 <sup>th</sup>	5.2. Construction, working principle and application of Universal motors.	
13 <sup>th</sup>	1 <sup>st</sup>	5.2. Construction, working principle and application of Universal motors.	
	2 <sup>nd</sup>	5.3. Working principle of Repulsion start Motor, Repulsion start Induction run motor, Repulsion Induction motor.	
	3 <sup>rd</sup>	5.3. Working principle of Repulsion start Motor, Repulsion start Induction run motor, Repulsion Induction motor.	
	4 <sup>th</sup>	6. SPECIAL ELECTRICAL MACHINE: 6.1. Principle of Stepper motor. 6.2. Classification of Stepper motor.	
<b>14</b> <sup>th</sup>	1 <sup>st</sup>	6.3. Principle of variable reluctant stepper motor. 6.6. Applications of Stepper motor.	
	2 <sup>nd</sup>	THREE PHASE TRANSFORMERS: 7.1. Explain Grouping of winding, Advantages.	
	3 <sup>rd</sup>	7.2. Explain parallel operation of the three phase transformers.	
	4 <sup>th</sup>	7.2. Explain parallel operation of the three phase transformers.	
15 <sup>th</sup>	1 <sup>st</sup>	7.3. Explain tap changer (On/Off load tap changing)	
	2 <sup>nd</sup>	7.3. Explain tap changer (On/Off load tap changing)	
	3 <sup>rd</sup>	7.4. Maintenance Schedule of Power Transformers.	
	4 <sup>th</sup>	7.4. Maintenance Schedule of Power Transformers.	



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Sign of H.O.D.