



NILASAILA INSTITUTE OF SCIENCE & TECHNOLOGY  
SERGARH-756060, BALASORE (ODISHA)  
(Approved by AICTE& affiliated to SCTE&VT, Odisha)



## LESSON PLAN

**SUBJECT: CEP203 TH-3 (MECHANICS OF MATERIALS)**

**Name Of The Faculty :-** Er. Kumar Swatiranjan

**Branch :-** Civil Engineering

**Academic Year :** 2025-26

**Semester :-** 3rd

**Examination :-** 2025 (w)

### CHAPTER WISE DISTRIBUTION OF PERIODS

Sl.No.	Name of the chapter as per the Syllabus	No. of Periods as per the Syllabus	No. of periods actually needed
1	Centre of Gravity and Moment of Inertia	8	8
2	Simple Stresses and Strains	12	15
3	Shear Force and Bending Moment	10	14
4	Bending and Shear Stresses in beams	9	13
5	Columns	6	10
	Total Period:	45	60

Sign of Faculty

Sign of H.O.D.

Name of the programme: Diploma in CIVIL ENGINEERING	Semester: 3rd	Name of the Teaching Faculty: Er. Kumar Swatiranjan	
		Academic Year : 2025-26	Examination : 2025 (W)
Course Code: CEP205 TH-3	Course Year: Second Year	No. of Classes Alloted Per Week :	4
		Planned Classes Required to Complete the Course	60
Week	Class Day	Topics to be Covered	
1 <sup>st</sup>	1 <sup>st</sup>	<b>UNIT-I:Centre of Gravity and Moment of Inertia</b> Definition of centre of gravity -Centre of gravity of of Symmetrical shapes ( solid / hollow square, rectangular, circular, I Sections.	
	2 <sup>nd</sup>	Moment of inertia (M.I.): Definition, M.I. of plane lamina, Radius of gyration, section mod- ulus, Parallel and Perpendicular axes theorems (without derivations).	
	3 <sup>rd</sup>	M.I. of rectangle, square, circle, semicircle, quarter circle and triangle section (without derivations).	
	4 <sup>th</sup>	M.I. of symmetrical and unsymmetrical I-section, Channel section.	
2 <sup>nd</sup>	1 <sup>st</sup>	M.I. of T-section, Angle section, Hollow sections.	
	2 <sup>nd</sup>	M.I. of built up sections about centroidal axes and any other reference axis.	
	3 <sup>rd</sup>	Polar Moment of Inertia of solid circular sections.	
	4 <sup>th</sup>	Polar Moment of Inertia of solid circular sections.	
3 <sup>rd</sup>	1 <sup>st</sup>	<b>UNIT-2:Simple Stresses and Strains</b> Definition of rigid, elastic and plastic bodies, deformation of elastic body under various forces, Definition of stress, strain, elasticity, Hook's law, Elastic limit, Modulus of elastic-ity.	
	2 <sup>nd</sup>	Type of Stresses-Normal, Direct, Bending and Shear and nature of stresses i.e. Tensile and Compressive stresses.	
	3 <sup>rd</sup>	Standard stress strain curve for tor steel bar under tension, Yield stress, Proof stress, Ultimate stress.	
	4 <sup>th</sup>	Strain at various critical points, Percentage elongation and Factor of safety.	
4 <sup>th</sup>	1 <sup>st</sup>	Deformation of body due to axial force, forces applied at intermediate sections.	
	2 <sup>nd</sup>	Maximum and minimum stress induced, Composite section under axial loading.	
	3 <sup>rd</sup>	Concept of temperature stresses and strain, Stress and strain developed due to temperature variation in homogeneous simple bar (no composite section).	
	4 <sup>th</sup>	Concept of temperature stresses and strain, Stress and strain developed due to temperature variation in homogeneous simple bar (no composite section).	

5 <sup>th</sup>	1 <sup>st</sup>	Longitudinal and lateral strain, Modulus of Rigidity, Poisson's ratio.
	2 <sup>nd</sup>	Biaxial and tri-axial stresses, volumetric strain, change in volume, Bulk modulus (Introduction only).
	3 <sup>rd</sup>	Relation between modulus of elasticity, modulus of rigidity and bulk modulus (without derivation).
	4 <sup>th</sup>	COMPLEX STRESSES AND STRAINS Principal stresses and strains: Occurrence of normal and tangential stresses - Concept of Principal stress and Principal Planes.
6 <sup>th</sup>	1 <sup>st</sup>	Major and minor principal stresses and their orientations – stresses on a given plane –shear and normal stress components on any inclined plane.
	2 <sup>nd</sup>	Mohr's circle and its use in solving problems on complex stresses - Numerical problems.
	3 <sup>rd</sup>	Mohr's circle and its use in solving problems on complex stresses - Numerical problems.
	4 <sup>th</sup>	<b>UNIT-3:Shear Force and Bending Moment</b> Types of supports, beams and loads.
7 <sup>th</sup>	1 <sup>st</sup>	Concept and definition of shear force and bending moment.
	2 <sup>nd</sup>	Relation between load, shear force and bending moment (without derivation).
	3 <sup>rd</sup>	Relation between load, shear force and bending moment (without derivation).
	4 <sup>th</sup>	Shear force and bending moment diagram for cantilever beams subjected to point loads.
8 <sup>th</sup>	1 <sup>st</sup>	Shear force and bending moment diagram for cantilever beams subjected to point loads.
	2 <sup>nd</sup>	Shear force and bending moment diagram for simply supported beams subjected to point loads.
	3 <sup>rd</sup>	Shear force and bending moment diagram for simply supported beams subjected to point loads.
	4 <sup>th</sup>	Shear force and bending moment diagram for simply supported beams subjected to point loads.
9 <sup>th</sup>	1 <sup>st</sup>	Shear force and bending moment diagram for uniformly distributed loads and couple (combination of any two types of loading).
	2 <sup>nd</sup>	Shear force and bending moment diagram for uniformly distributed loads and couple (combination of any two types of loading).
	3 <sup>rd</sup>	Shear force and bending moment diagram for uniformly distributed loads and couple (combination of any two types of loading).
	4 <sup>th</sup>	Shear force and bending moment diagram for uniformly distributed loads and couple (combination of any two types of loading).

10 <sup>th</sup>	1 <sup>st</sup>	Determination of point of contra flexure.
	2 <sup>nd</sup>	<b>UNIT-4:Bending and Shear Stresses in beams</b> Concept and theory of pure bending, assumptions, flexural equation (without derivation).
	3 <sup>rd</sup>	Bending stresses and their nature.
	4 <sup>th</sup>	Bending stress distribution diagram.
11 <sup>th</sup>	1 <sup>st</sup>	Concept of moment of resistance and simple numerical problems using flexural equation.
	2 <sup>nd</sup>	Concept of moment of resistance and simple numerical problems using flexural equation.
	3 <sup>rd</sup>	Shear stresss equation (without derivation).
	4 <sup>th</sup>	Relation between maximum and average shear stress for rectangular and circular section.
12 <sup>th</sup>	1 <sup>st</sup>	Shear stress distribution diagram.
	2 <sup>nd</sup>	Shear stress distribution for square, rectangular, circle, hollow, square, rectangular, circular.
	3 <sup>rd</sup>	Shear stress distribution for angle sections, channel section.
	4 <sup>th</sup>	Shear stress distribution for angle sections, channel section.
13 <sup>th</sup>	1 <sup>st</sup>	I-section, T section. Simple numerical problems based on shear equation.
	2 <sup>nd</sup>	I-section, T section. Simple numerical problems based on shear equation.
	3 <sup>rd</sup>	<b>UNIT-5:Columns</b> Concept of compression member
	4 <sup>th</sup>	Short and long column, Effective length, Radius of gy- ration, Slenderness ratio.
14 <sup>th</sup>	1 <sup>st</sup>	Types of end condition for columns, Buckling of axially loadedcolumns.
	2 <sup>nd</sup>	Euler's theory, assumptions made in Euler's theory and its limitations
	3 <sup>rd</sup>	Application of Eu- ler's equation to calculate buckling load.
	4 <sup>th</sup>	Application of Eu- ler's equation to calculate buckling load.
15 <sup>th</sup>	1 <sup>st</sup>	Rankine' s formula and its application to calculate crippling load.
	2 <sup>nd</sup>	Rankine' s formula and its application to calculate crippling load.
	3 <sup>rd</sup>	Concept of working load/safe load, design load and factor of safety.
	4 <sup>th</sup>	Concept of working load/safe load, design load and factor of safety.

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10-7-2025

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10-7-2025

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